Constant Amplitude and Zero Autocorrelation Sequences and Single Pixel Camera Imaging

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Frames

A finite frame for \mathbb{C}^N is a set $\mathcal{F} = \{v_j\}_{j=1}^M$ such that there exists constants $0 < A \le B < \infty$ where

$$A\|x\|_{2}^{2} \leq \sum_{j=1}^{M} |\langle x, v_{j}
angle|^{2} \leq B\|x\|_{2}^{2}$$

for any $x \in \mathbb{C}^N$. \mathcal{F} is called a *tight frame* if A = B is possible.

Theorem

 \mathcal{F} is a frame for \mathbb{C}^N if and only if \mathcal{F} spans \mathbb{C}^N .



The Frame Operator

Let $\mathcal{F} = \{v_j\}_{j=1}^M$ be a frame for \mathbb{C}^N and $x \in \mathbb{C}^N$. (a) The frame operator, $S : \mathbb{C}^N \to \mathbb{C}^N$, is given by

$$S(x) = \sum_{j=1}^{M} \langle v_j, x \rangle v_j.$$

(b) Given any $x \in \mathbb{C}^N$ we can write x in terms of frame elements by

$$x = \sum_{j=1}^{M} \langle x, S^{-1} v_j \rangle v_j.$$

(c) If \mathcal{F} is a tight frame with bound A, then $S = A Id_N$.



Gabor Frames

Definition

(a) Let $\varphi \in \mathbb{C}^N$ and $\Lambda \subseteq (\mathbb{Z}/N\mathbb{Z}) \times (\mathbb{Z}/N\mathbb{Z})$. The Gabor system, (φ, Λ) is defined by

$$(\varphi, \Lambda) = \{ e_{\ell} \tau_k \varphi : (k, \ell) \in \Lambda \}.$$

(b) If (φ, Λ) is a frame for \mathbb{C}^N we call it a Gabor frame.



Time-Frequency Transforms

Definition

Let $\varphi, \psi \in \mathbb{C}^N$.

(a) The discrete periodic ambiguity function of φ, A_p(φ), is defined by

$$A_{\rho}(\varphi)[k,\ell] = \frac{1}{N} \sum_{j=0}^{N-1} \varphi[j+k] \overline{\varphi[j]} e^{-2\pi i j \ell/N} = \frac{1}{N} \langle \tau_{-k} \varphi, e_{\ell} \varphi \rangle.$$

(b) The short-time Fourier transform of φ with window ψ , $V_{\psi}(\varphi)$, is defined by

$$V_{\psi}(\varphi)[k,\ell] = \langle \varphi, \mathbf{e}_{\ell}\tau_{k}\psi \rangle.$$



Full Gabor Frames Are Always Tight

Theorem Let $\varphi \in \mathbb{C}^N \setminus \{0\}$. and $\Lambda = (\mathbb{Z}/N\mathbb{Z}) \times (\mathbb{Z}/N\mathbb{Z})$. Then, (φ, Λ) is always a tight frame with frame bound $N \|\varphi\|_2^2$.



Finite Gabor Frames

Janssen's Representation

Definition

Let $\Lambda \subseteq (\mathbb{Z}/N\mathbb{Z}) \times (\mathbb{Z}/N\mathbb{Z})$ be a subgroup. The *adjoint subgroup* of Λ , $\Lambda^{\circ} \subseteq (\mathbb{Z}/N\mathbb{Z}) \times (\mathbb{Z}/N\mathbb{Z})$, is defined by

$$\Lambda^{\circ} = \{ (m, n) : e_{\ell} \tau_k e_n \tau_m = e_n \tau_m e_{\ell} \tau_k, \forall (k, \ell) \in \Lambda \}$$

Theorem

Let Λ be a subgroup of $(\mathbb{Z}/N\mathbb{Z}) \times (\mathbb{Z}/N\mathbb{Z})^{\widehat{}}$ and $\varphi \in \mathbb{C}^{N}$. Then, the (φ, Λ) Gabor frame operator has the form

$$S = \frac{|\Lambda|}{N} \sum_{(m,n)\in\Lambda^{\circ}} \langle \varphi, e_n \tau_m \varphi \rangle e_n \tau_m.$$



$\Lambda^\circ\text{-sparsity}$ and Tight Frames

Theorem

Let $\varphi \in \mathbb{C}^N \setminus \{0\}$ and let $\Lambda \subseteq (\mathbb{Z}/N\mathbb{Z}) \times (\mathbb{Z}/N\mathbb{Z})$ be a subgroup. (φ, Λ) is a tight frame if and only if

$$\forall (m,n) \in \Lambda^{\circ}, (m,n) \neq 0, \quad A_{\rho}(\varphi)[m,n] = 0.$$

The frame bound is $|\Lambda|A_p(\varphi)[0,0]$.



Proof of Λ° -sparsity Theorem

By Janssen's representation we have

$$S = \frac{|\Lambda|}{N} \sum_{(m,n)\in\Lambda^{\circ}} \langle e_n \tau_m \varphi, \varphi \rangle e_n \tau_m = \sum_{(m,n)\in\Lambda^{\circ}} \langle \tau_m \varphi, e_{-n} \varphi \rangle e_n \tau_m$$
$$= |\Lambda| \sum_{(m,n)\in\Lambda^{\circ}} A_p(\varphi) [-m, -n] e_n \tau_m = |\Lambda| \sum_{(m,n)\in\Lambda^{\circ}} A_p(\varphi) [m, n] e_{-n} \tau_{-m}.$$

If $A_p(\varphi)[m, n] = 0$ for every $(m, n) \in \Lambda^\circ$, $(m, n) \neq 0$, then S is $|\Lambda|A_p(\varphi)[0, 0]$ times the identity. and so (φ, Λ) is a tight frame.



To show this is a necessary condition, we observe that for S to be tight we need

$$S = |\Lambda| \sum_{(m,n) \in \Lambda^{\circ}} A_p(\varphi)[m,n] e_n \tau_m = A \, ld$$

which can be rewritten as

 $\sum_{(m,n)\in\Lambda^{\circ}\setminus\{(0,0)\}}|\Lambda|A_{p}(\varphi)[m,n]e_{n}\tau_{m}+(|\Lambda|A_{p}(\varphi)[0,0]-A)Id=0.$



Let $\varphi \in \mathbb{C}^N$. φ is said to be a *constant amplitude zero autocorrelation (CAZAC) sequence* if

$$orall j \in (\mathbb{Z}/N\mathbb{Z}), |arphi_j| = 1$$
 (CA)

and

$$\forall k \in (\mathbb{Z}/N\mathbb{Z}), k \neq 0, \frac{1}{N} \sum_{j=0}^{N-1} \varphi_{j+k} \overline{\varphi_j} = 0.$$
 (ZAC)



Quadratic Phase Sequences

Let $\varphi \in \mathbb{C}^N$ and suppose for each j, φ_j is of the form $\varphi_j = e^{-\pi i p(j)}$ where p is a quadratic polynomial. The following quadratic polynomials generate CAZAC sequences:

• Chu:
$$p(j) = j(j-1)$$

• P4:
$$p(j) = j(j - N)$$
, N is odd

- ▶ Odd-length Wiener: $p(j) = sj^2$, gcd(s, N) = 1, N is odd
- Even-length Wiener: $p(j) = sj^2/2$, gcd(s, 2N) = 1, N is even



Examples

Björck Sequences

Let p be prime and $\varphi \in \mathbb{C}^p$ be of the form $\varphi_j = e^{i\theta(j)}$. Then φ will be CAZAC in the following cases:

lf $p \equiv 1 \mod 4$, then,

$$heta(j) = \left(rac{j}{p}
ight) \arccos\left(rac{1-p}{1+\sqrt{p}}
ight)$$

lf $p \equiv 3 \mod 4$, then,

$$\begin{cases} \arccos\left(\frac{1-p}{1+p}\right), & \text{if } \left(\frac{j}{p}\right) = -1\\ 0, & \text{otherwise} \end{cases}$$



Connection to Hadamard Matrices

Theorem

Let $\varphi \in \mathbb{C}^N$ and let H be the circulant matrix given by

$$H = \begin{bmatrix} & \varphi & & \\ & & \tau_1 \varphi & & \\ & & \tau_2 \varphi & & \\ & & \ddots & \\ & & & \tau_{N-1} \varphi & & \end{bmatrix}$$

Then, φ is a CAZAC sequence if and only if H is Hadamard. In particular there is a one-to-one correspondence between CAZAC sequences and circulant Hadamard matrices.



Connection to Cyclic N-roots

Definition

 $x \in \mathbb{C}^N$ is a cyclic *N*-root if it satisfies

$$\begin{cases} x_0 + x_1 + \dots + x_{N-1} = 0\\ x_0 x_1 + x_1 x_2 + \dots + x_{N-1} x_0 = 0\\ \dots\\ x_0 x_1 x_2 \dots x_{N-1} = 1 \end{cases}$$



Connection to Cyclic N-roots

Theorem

(a) If $\varphi \in \mathbb{C}^N$ is a CAZAC sequence then,

$$\left(\frac{\varphi_1}{\varphi_0}, \frac{\varphi_2}{\varphi_1}, \cdots, \frac{\varphi_0}{\varphi_{N-1}}\right)$$

is a cyclic N-root. (b) If $x \in \mathbb{C}^N$ is a cyclic N-root then,

$$\varphi_0 = x_0, \varphi_j = \varphi_{j-1} x_j$$

is a CAZAC sequence.

(c) There is a one-to-one correspondence between CAZAC sequences which start with 1 and cyclic N-roots.



5-Operation Equivalence

Proposition

Let $\varphi \in \mathbb{C}^N$ be a CAZAC sequence. Then, the following are also CAZAC sequences:

(a)
$$\forall c \in \mathbb{C}, |c| = 1, c\varphi$$

(b) $\forall k \in \mathbb{Z}/N\mathbb{Z}, \tau_k \varphi$
(c) $\forall \ell \in (\mathbb{Z}/N\mathbb{Z}), e_\ell \varphi$
(d) $\forall m \in \mathbb{Z}/N\mathbb{Z}, gcd(m, N) = 1, \pi_m \varphi[j]$
(e) $n = 0, 1, c_n \varphi$
The operation π_m is defined by $\pi_m \varphi[j] = \varphi[mj]$ and c_0, c_1 is
defined by $c_0 \varphi = \varphi$ and $c_1 \varphi = \overline{\varphi}$.



5-Operation Group Action

Let G be the set given by

 $\{(a,b,c,d,f):a\in\{0,1\},b,c,d,f\in\mathbb{Z}/p\mathbb{Z},c\neq0\}$

and define the operation $\cdot: G \times G \rightarrow G$ by

 $(a, b, c, d, f) \cdot (h, j, k, \ell, m)$ = $(a + h, cj + b, ck, \ell + (-1)^h kd, m + (-1)^h (f - jc)).$ Then, (G, \cdot) is a group of size $2p^3(p - 1)$.



5-Operation Group Action (cont'd)

- ► To each element $(a, b, c, d, f) \in G$ we associate the operator $\omega_f e_d \pi_c \tau_b c_a$, which form a group under composition, where $\omega = e^{2\pi i/p}$.
- ▶ The composition is computed by the operation for (*G*, ·) and obtaining the operator associated with the computed result.
- The group of operators under composition forms a group action for U^p_p, the set of *p*-length vectors comprised entirely of *p*-roots of unity.
- ► There are p(p − 1) many CAZACs in U^p_p which start with 1. Adding in any scalar multiples of roots of unity, there are p²(p − 1) many.



5-Operation Orbits

Theorem

Let p be an odd prime and let $\varphi \in U_p^p$ be the Wiener sequence $\varphi[n] = e^{2\pi i s n^2/p}$, where $s \in \mathbb{Z}/p\mathbb{Z}$. Denote the stabilizer of φ under the group (G, \cdot) as G_{φ} . If $p \equiv 1 \mod 4$, then $|G_{\varphi}| = 4p$. If $p \equiv 3 \mod 4$, then $|G_{\varphi}| = 2p$. In particular, the orbit of φ has size $p^2(p-1)/2$ if $p \equiv 1 \mod 4$ and size $p^2(p-1)$ if $p = 3 \mod 4$.



Sketch of Proof

- Take a linear operator $\omega_f e_d \pi_c \tau_b c_a$ and write the system of equations that would describe fixing each term of $\varphi[n]$.
- Use the n = 0, 1 cases to get expressions for f and d in terms of the other variables.
- Use any other n > 1 and substitute the expressions for f and d to obtain the condition

$$c^2 \equiv (-1)^a \mod p.$$



Sketch of Proof (con't)

- In the case a = 0, there are always the solutions c ≡ ±1 mod p. If a = 1, then it depends if −1 is a quadratic residue modulo p. It is if p ≡ 1 mod 4 and is not if p ≡ 3 mod 4.
- All variables are solved for except b and the solutions leave it as a free parameter. Thus there are 4p and 2p stabilizers for the p ≡ 1 mod 4 and p ≡ 3 mod 4 cases respectively.



DPAF of Chu Sequence

$$egin{aligned} &A_{m{
ho}}(arphi_{\mathsf{Chu}})[k,\ell]:\ &iggle e^{\pi i (k^2-k)/N}, \ k\equiv\ell ext{ mod }N\ 0, & ext{otherwise} \end{aligned}$$

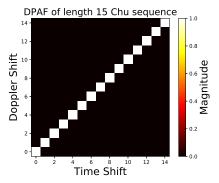


Figure: DPAF of length 15 Chu sequence.



Finite Gabor Frames

Proposition

Let N = abN' where gcd (a, b) = 1 and $\varphi \in \mathbb{C}^N$ be the Chu or P4 sequence. Define $K = \langle a \rangle$, $L = \langle b \rangle$ and $\Lambda = K \times L$.

(a)
$$\Lambda^{\circ} = \langle N'a \rangle \times \langle N'b \rangle$$
.

(b) (φ, Λ) is a tight Gabor frame bound NN'.



DPAF of Even Length Wiener Sequence

$$egin{aligned} &A_{eta}(arphi_{ ext{Wiener}})[k,\ell]:\ &iggin{aligned} &\epsilon^{\pi i s k^2/N}, \ sk\equiv\ell ext{ mod }N\ &0, & ext{otherwise} \end{aligned}$$

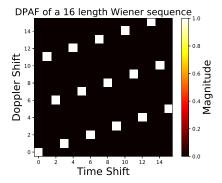


Figure: DPAF of length 16 P4 sequence.



Finite Gabor Frames

DPAF of Björck Sequence

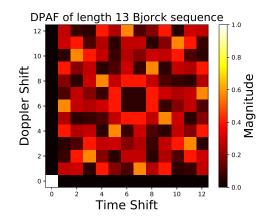


Figure: DPAF of length 13 Björck sequence.



DPAF of a Kronecker Product Sequence

Kronecker Product: Let $u \in \mathbb{C}^M$, $v \in \mathbb{C}^N$. $(u \otimes v)[aM + b] = u[a]v[b]$

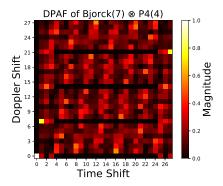


Figure: DPAF of Kroneker product of length 7 Bjorck and length 4 P4.



Example: Kronecker Product Sequence

Proposition

Let $u \in \mathbb{C}^M$ be CAZAC, $v \in \mathbb{C}^N$ be CA, and $\varphi \in \mathbb{C}^{MN}$ be defined by the Kronecker product: $\varphi = u \otimes v$. If gcd (M, N) = 1 and $\Lambda = \langle M \rangle \times \langle N \rangle$, then (φ, Λ) is a tight frame with frame bound MN.



Definition

Let $\mathcal{F} = \{v_i\}_{i=1}^M$ be a frame for \mathbb{C}^N . The *Gram matrix*, *G*, is defined by

 $G_{i,j} = \langle v_i, v_j \rangle.$

In the case of Gabor frames $\mathcal{F} = \{e_{\ell_m} \tau_{k_m} \varphi : m \in 0, \cdots, M-1\}$, we can write the Gram matrix in terms of the discrete periodic ambiguity function of φ :

$$G_{m,n} = N e^{-2\pi i k_n (\ell_n - \ell_m)/N} A_p(\varphi) [k_n - k_m, \ell_n - \ell_m]$$



Gram Matrix of Chu and P4 Sequences

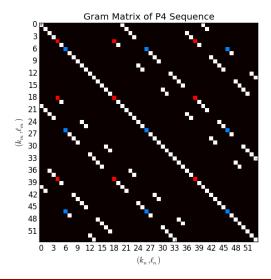
Lemma

Let $\varphi \in \mathbb{C}^N$ be the Chu or P4 sequence and let N = abN' where gcd(a, b) = 1. Suppose G is the Gram matrix generated by the Gabor system $(\varphi, K \times L)$ where $K = \langle a \rangle$ and $L = \langle b \rangle$. Then,

- (a) The support of the rows (or columns) of G either completely conincide or are completely disjoint.
- (b) If two rows (or columns) have coinciding supports, they are scalar multiples of each other.



Example: P4 Gram Matrix





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Finite Gabor Frames

Theorem

Let $\varphi \in \mathbb{C}^N$ be the Chu or P4 sequence and let N = abN' where gcd(a, b) = 1. Suppose G is the Gram matrix generated by the Gabor system $(\varphi, K \times L)$ where $K = \langle a \rangle$ and $L = \langle b \rangle$. Then, (a) rank(G) = N.

(b) G has exactly one nonzero eigenvalue, NN'.

In particular (a) and (b) together imply that the Gabor system $(\varphi, K \times L)$ is a tight frame with frame bound NN'.



Proof

K ∩ L = ⟨ab⟩.
G_{mn} ≠ 0 if and only if (l_n - l_m) ≡ (k_n - k_m) mod N.
This can only occur at the intersection of K and L, i.e., ∀j ∈ (ℤ/N'ℤ), (l_n - l_m) ≡ (k_n - k_m) ≡ jab mod N
Fix an m, we can write k_n as k_n = a(j_m + jb) for some j
By the column ordering of G we can write the n-th column by

$$n = k_n N' + \ell_n / b$$



Proof (con't)

- We want to look at the first N columns so we want n < N and thus require k_n < ab.</p>
- Thus, $(j_m + jb) < b$.
- There is exactly one such $j \in (\mathbb{Z}/N'\mathbb{Z})$ and it is $j = -\lfloor j_m/b \rfloor$.
- Consequently, for each row m, there is exactly 1 column n ≤ N where G_{mn} ≠ 0 and the first N columns of G are linearly independent.

▶ rank(
$$G$$
) = N .



Proof (con't)

- Let g_n be the *n*-th column of G, n < N.
- The goal is to show that $Gg_n = NN'g_n$.
- $Gg_n[m]$ is given by the inner product of row m and column n.
- The n-th column is the conjugate of the n-th row.
- If $Gg_n[m] \neq 0$, then $G_{mn} \neq 0$ and $G_{nn} \neq 0$.



Proof (con't)

- Lemma implies row m and n have coinciding supports and are constant multiples of each other thus, G_{m(·)} = C_mg^{*}_n where |C_m| = 1.
- Therefore, $Gg_n[m] = C_m ||g_n||_2^2 = N^2 N' C_m$.

•
$$G_{nn} = N$$
, so $g_n[m] = NC_m$.

▶ Finally, Gg_n[m] = (NN')(NC_m) and we conclude the first N columns of G are eigenvectors of G with eigenvalue NN'.



Future work: Continuous CAZAC Property

Is it possible to generalize CAZAC to the real line? The immediate problem is the natural inner product to use for autocorrelation is the $L^2(\mathbb{R})$ inner product, but if |f(x)| = 1 for every $x \in \mathbb{R}$, then clearly $f \notin L^2(\mathbb{R})$.



Future work: Continuous CAZAC Property

Alternatives and ideas:

- Define a continuous autocorrelation on L²(T) and push torus bounds to infinity.
- Distribution theory, esp. using tempered distributions.
- ▶ Wiener's Generalized Harmonic Analysis, which includes a theory of mean autocorrelation on ℝ.



Future work: Single Pixel Camera

- My work on this is with John Benedetto and Alfredo Nava-Tudela and is an ongoing project.
- The original concept is due to Richard Baraniuk.
- The idea is to construct a camera using only a single light receptor or sensor.
- This is accomplished by filtering through a pixel grid that either admits or blocks light.
- Baraniuk's original design does this with digital micromirror devices.
- Several collections with different pixel grids are required but compressed sensing theory allows this to be done efficiently.



Questions?



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